Chapter 8, Part 2

# NL and L

#### **NL-Completeness**

A **logspace** transducer is a TM with a read-only input tape, a write-only output tape, and a read/write work tape, in which only  $O(\log n)$  tape cells of the work tape can be used.

A logspace transducer M computes a function f if for every w, M on w halts with f(w) on the output tape.

A language A is **logspace reducible**, write  $A \leq_L B$ , if there is a logspace computable mapping reduction from A to B.

A language L is **NL-complete** if  $A \in \mathbf{NL}$  and every  $A \in \mathbf{NL}$  is logspace reducible to L.

#### **Properties of logspace reductions**

**Theorem.** If  $A \leq_L B$  and  $B \in \mathbf{L}$  then  $A \in \mathbf{L}$ .

If  $A \leq_L B$  and  $B \in \mathbf{NL}$  then  $A \in \mathbf{NL}$ .

**Theorem.** If A is NL-complete and  $A \in \mathbf{L}$  then  $\mathbf{L} = \mathbf{NL}$ .

## **Theorem.** *PATH* is **NL-complete.**

**Proof**  $PATH \in \mathbf{NL}$ . Given an instance (G, s, t) of PATH with n nodes, repeat the following n - 1 times with x = s at the beginning:

- Nondeterministically select a node y from  $1,\ldots,n$ ,
- If (x, y) is in G, then set x to y. If not, reject.
- If y = t, then accept.

This method correctly decides whether  $(G, s, t) \in PATH$  and requires  $O(\log n)$  space.

## **PATH** is NL-complete (cont'd)

Let L be decided by a nondeterministic  $c \log n$  space machine N. We may assume that N has the unique accepting configuration for each input. Let x be an input of some length n. Define the graph G as follows:

- The nodes of G are the configurations of M on x. Here each configuration is the concatenation of the state, head positions, and the work tape contents.
- s is the initial configuration
- t is the accepting configuration.
- For every pair of nodes u and v, there is an arc from u to v if and only if v is one of the next possible configurations of u.

Then  $(G, s, t) \in PATH$  if and only if  $x \in L$ .

# Computation of (G, s, t) in logspace

Let  $\ell$  be the encoding length of each configuration.

for  $u = 0^{\ell}, ..., 1^{\ell}$  do for  $v = 0^{\ell}, ..., 1^{\ell}$  do if u and v are configurations then if  $u \Rightarrow v$  then output 1 else output 0  $C \leftarrow 0$ : for  $u = 0^{\ell}, ..., 1^{\ell}$  do if u is a configuration then  $C \leftarrow C + 1$ : if u = the initial config. then output "s = C" if u = the accepting config. then output "t = C" The algorithm works in  $O(\ell) = O(\log n)$  space.

#### NL = coNL

## Theorem. $\overline{PATH} \in \mathbf{NL}$ .

**Proof** Let (G, s, t) be an instance of *PATH* with *n* nodes. For each *i*,  $0 \le i \le n$ , define  $A_i$  to be the set of all nodes reachable from *s* within *i* steps and  $c_i = ||A_i||$ .

Given  $c_i$  it is possible to nondeterministically enumerate all the nodes in  $A_i$  with the following ENUMERATE $(i, c_i)$ :

- 1. Set counter d to 0;
- 2. for j = 0,...,n do the following:
  (a) guess an s-to-j path of length at most i;
  (b) if successful increment d and output j;
- 3. if  $d = c_i$  output "SUCCESSFUL"; otherwise, output "FAILURE"

Computing  $c_{i+1}$  knowing  $c_i$ 

- 1. Set counter e to 0;
- 2. For  $j = 0, \ldots, n$  do the following:
  - (a) Set a variable r to false.
  - (b) Call ENUMERATE(*i*,  $c_i$ ). For each node u output by ENUMERATE, check if  $u \Rightarrow j$ ; if so, set r to true.
  - (c) If ENUMERATE has output "FAILURE" at the end output "FAILURE".

Otherwise, increment e if and only if r = true.

3. Output *e*.

## **Testing Unreachability**

- 1. Set i to 0 and  $c_0$  to 1.
- 2. For  $i = 0, \ldots, n-1$ , compute  $c_{i+1}$  from  $c_i$ .
- 3. (Check if  $t \notin A_n$  by calling ENUMERATE $(n, c_n)$ .) Accept if the enumeration is "SUCCESSFUL" and t is not output.

The method uses only  $O(\log n)$  space.